

	\hat{x}	\hat{y}	\hat{z}
\hat{r}	$\cos\phi$	$\sin\phi$	0
$\hat{\phi}$	$-\sin\phi$	$\cos\phi$	0
\hat{z}	0	0	1

Rectangular and cylindrical

	\hat{x}	\hat{y}	\hat{z}
\hat{R}	$\sin\theta\cos\phi$	$\sin\theta\sin\phi$	$\cos\theta$
$\hat{\theta}$	$\cos\theta\cos\phi$	$\cos\theta\sin\phi$	$-\sin\theta$
$\hat{\phi}$	$-\sin\phi$	$\cos\phi$	0

Rectangular and spherical

	\hat{r}	$\hat{\phi}$	\hat{z}
\hat{R}	$\sin\theta$	0	$\cos\theta$
$\hat{\theta}$	$\cos\theta$	0	$-\sin\theta$
$\hat{\phi}$	0	1	0

Cylindrical and spherical

Example: from top table, reading across,

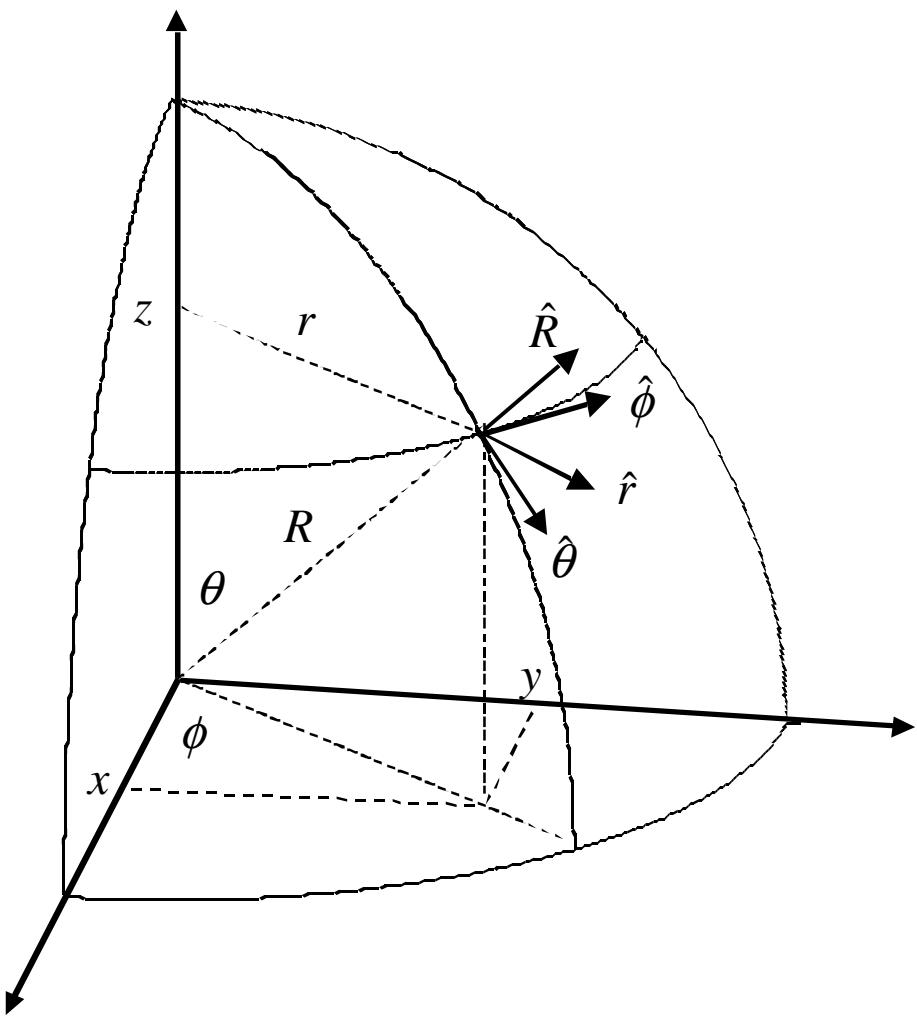
$$\hat{r} = \hat{x}\cos\phi + \hat{y}\sin\phi$$

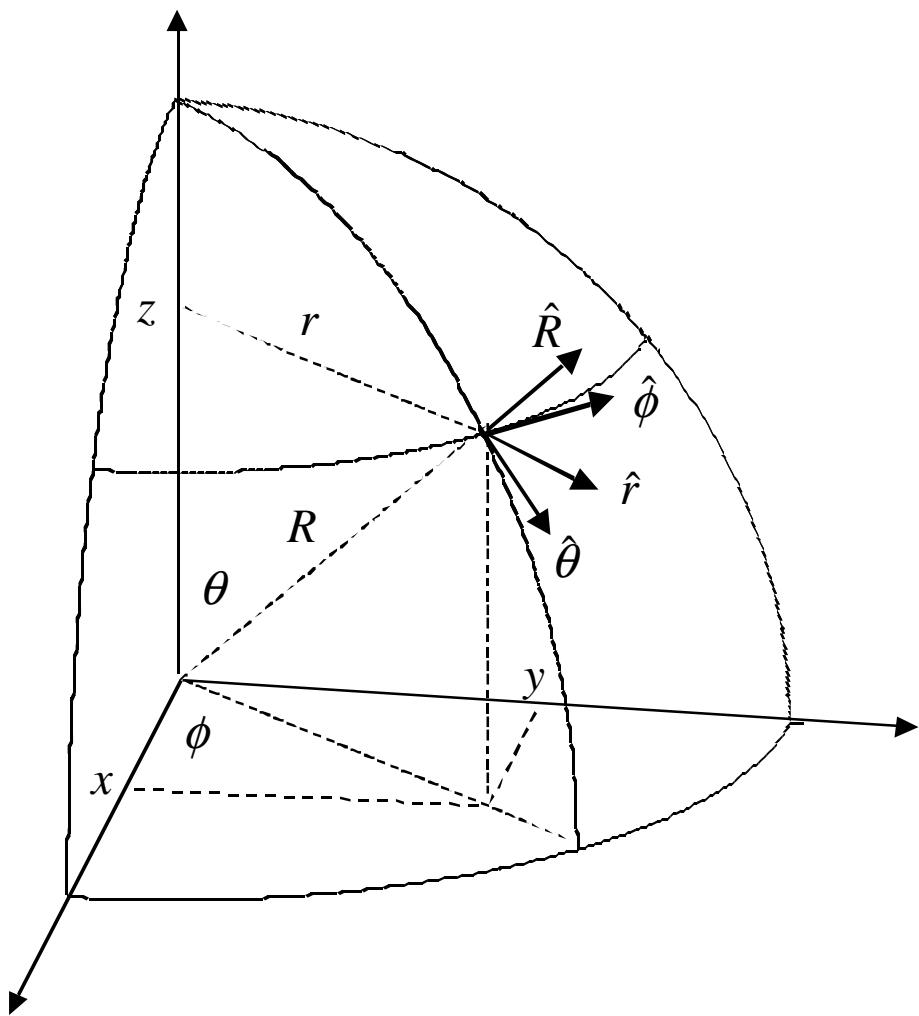
and reading down,

$$\hat{x} = \hat{r}\cos\phi - \hat{\phi}\sin\phi$$

The tables also be used to transform vectors. For example, given $\vec{A} = A_x\hat{x} + A_y\hat{y} + A_z\hat{z}$ in cartesian coordinates, the vector can be expressed in cylindrical coordinates

$$A_r = A_x \cos\phi + A_y \sin\phi + A_z \cdot 0$$





$$R = \sqrt{x^2 + y^2 + z^2} = \sqrt{r^2 + z^2}$$

$$\phi = \tan^{-1}\left(\frac{y}{x}\right)$$

$$\theta = \tan^{-1}\left(\frac{r}{z}\right)$$